

$$H = \int (N_{\perp} K_{\perp} + N_a K^a) d^3x$$

$$K_{\perp} = \sqrt{h} \left[h^{-1} (\pi^{ab} \pi_{ab} - \frac{1}{2} (\pi^a_a)^2 - {}^3R) \right]$$

$$K^a = -D_b \pi^{ab}$$

Densities:

$$\int_{\mathcal{R}} \sqrt{h} d^3x : \text{geometric volume (invariant)}$$

$$\int_{\mathcal{R}} f(x) \sqrt{h} d^3x : \text{invariant.}$$

So $K_{\perp}$ and K^a should have weight 1

$\sqrt{h}$ — scalar density of weight 1

1) π^{ab} is a tensor density of wt. 1 :

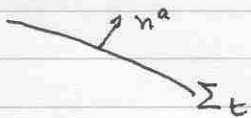
$$\pi^{ab} = \frac{\delta L}{\delta h_{ab}} = \sqrt{h} \underbrace{(K^{ab} - K h^{ab})}_{\substack{\text{tensor of wt. 0} \\ \uparrow \\ \text{wt. 1}}}$$

→ But just by the definition of the variation of a scalar:

$$\delta L = \underbrace{\frac{\delta L}{\delta h_{ab}}}_{\text{must be scalar density of wt. 1}} \delta h_{ab} d^3x$$

must be scalar density of wt. 1 $\Rightarrow \frac{\delta L}{\delta h_{ab}}$ has wt. 1

2)



$h_{ab} = g_{ab} + n_a n_b$, purely spatial tensor. In the Hamiltonian formalism, we restrict g_{ab} to Σ_t to obtain a 3-D Riemannian metric (+++).

3) Why " $\cdot$ " = $\mathcal{L}_t$?

$$\begin{cases} \dot{h}_{ab} = \mathcal{L}_t h_{ab} = \frac{\delta H}{\delta \pi^{ab}} \\ \dot{\pi}^{ab} = \mathcal{L}_t \pi^{ab} = -\frac{\delta H}{\delta h_{ab}} \end{cases}$$

In a coord (t, x^i) , ~~$\mathcal{L}_t = \partial_t$~~
 $\mathcal{L}_t = \partial_t = "$

See that, $t^c \nabla_c h_{ab}$ depends on the dynamical variables ($\nabla = \nabla(g)$) whereas $\mathcal{L}_t$ does not.

also, $\delta H = \int \underbrace{\frac{\delta H}{\delta \pi}}_{\text{wt. 0}} \underbrace{\delta \pi}_{\text{wt. 1}} d^3x$

K^a — spatial diffeomorphism constraint.

$$\int N_a K^a d^3x = \int -N_a D_b \pi^{ab} d^3x = \int \left[(D_a N_b) \pi^{ab} - \underbrace{D_a (N_b \pi^{ab})}_{\substack{\text{vector density} \\ \text{surface term}}} \right] d^3x =$$

$$= \frac{1}{2} \int \mathcal{L}_N h_{ab} \pi^{ab} d^3x.$$