

Solution To PHYS622 Homework Set 10

1 Solution1

(a).

$$\begin{aligned} T_{\vec{d}}\psi(\vec{x}) &= \psi(\vec{x} + \vec{d}) \\ T_{\vec{d}'}T_{\vec{d}}\psi(\vec{x}) &= \psi(\vec{x} + \vec{d}' + \vec{d}) \\ T_{\vec{d}}T_{\vec{d}'}\psi(\vec{x}) &= \psi(\vec{x} + \vec{d} + \vec{d}') \\ \implies [T_{\vec{d}}, T_{\vec{d}'}] &= 0 \end{aligned}$$

(b). $D(\hat{n}, \phi)$ does not commute with $D(\hat{n}', \phi')$.

(c). $T_{\vec{d}}$ and Π do not commute.

$$\begin{aligned} \Pi T_{\vec{d}}\psi(\vec{x}) &= \psi(-\vec{x} - \vec{d}) \\ T_{\vec{d}}\Pi\psi(\vec{x}) &= \psi(-\vec{x} + \vec{d}) \end{aligned}$$

(d).

$$\Pi D(\hat{n}, \phi)\psi(\vec{x}) = \Pi\psi(\vec{x}') = \psi(-\vec{x}'), \vec{x}' = D(\hat{n}, \phi)\vec{x}.$$

On the other hand

$$D(\hat{n}, \phi)\Pi\psi(\vec{x}) = D(\hat{n}, \phi)\psi(-\vec{x}) = \psi(-\vec{x}')$$

They commute.

2 Solution2

(a).

$$\begin{aligned} y_l^{j=l\pm 1/2, m} &= \frac{1}{\sqrt{2l+1}} \begin{pmatrix} \pm\sqrt{l\pm m+1/2}Y^{m-1/2} \\ \sqrt{l\mp m+1/2}Y^{m+1/2} \end{pmatrix} \\ y_{l=0}^{j=1/2, m=1/2} &= \frac{1}{\sqrt{4\pi}} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{aligned}$$

(b).

$$\begin{aligned} \vec{\sigma} \cdot \vec{x} \frac{1}{\sqrt{4\pi}} \begin{pmatrix} 1 \\ 0 \end{pmatrix} &= \frac{1}{\sqrt{4\pi}} \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{r}{\sqrt{2\pi}} \begin{pmatrix} \cos\theta \\ \sin\theta e^{i\phi} \end{pmatrix} \\ &= -r \begin{pmatrix} -Y_1^0(\theta, \phi)/\sqrt{3} \\ Y_1^1(\theta, \phi)/\sqrt{2/3} \end{pmatrix} = -ry_{l=1}^{j=1/2, m=1/2} \end{aligned}$$

(c). $\vec{S} \cdot \vec{x}$ is a scalar(spherical tensor of rank 0)under rotation,hence by Wigner-Eckart theorem it cannot change j and m.But under space inversion $\vec{S} \cdot \vec{x}$ is odd.So $\vec{S} \cdot \vec{x}$ connects even parity with odd parity,and we note $l=0$ and $l=1$ have opposite parity.

3 Solution3

Symmetric states

$$\begin{aligned}\psi_I &= A \sin(k_s(x + a + b)) \\ \psi_{II} &= B \cosh(\kappa_s x) \\ \psi_{III} &= -A \cosh(\kappa_s(x - a - b))\end{aligned}$$

Antisymmetric states

$$\begin{aligned}\phi_I &= C \sin(k_s(x + a + b)) \\ \phi_{II} &= D \cosh(\kappa_s x) \\ \phi_{III} &= C \cosh(\kappa_s(x - a - b))\end{aligned}$$

All of states should satisfy Schrodinger's equations and appropriate boundary conditions. Matching the solutions and derivatives at each boundary we could have

$$\begin{aligned}k_s &= \frac{\pi}{b + \coth \kappa a / \kappa} \\ k_a &= \frac{\pi}{b + \tanh \kappa a / \kappa}\end{aligned}$$

The lowest lying states are

$$\begin{aligned}E_s &= \frac{\hbar^2 k_s^2}{2m} = \frac{\hbar^2 \pi^2}{2m(b + \coth \kappa a / \kappa)^2} \\ E_a &= \frac{\hbar^2 k_a^2}{2m} = \frac{\hbar^2 \pi^2}{2m(b + \tanh \kappa a / \kappa)^2}\end{aligned}$$

Therefore,

$$\Delta = E_a - E_s = \frac{\hbar^2 \pi^2}{2mb^2[(1 + \tanh \kappa a / \kappa b)^2 - (1 + \coth \kappa a / \kappa b)^2]}$$

4 Solution4

(a).

$$\psi(\vec{x}, t) = e^{i(\vec{p} \cdot \vec{x} / \hbar - \omega t)}$$

$$\psi^*(\vec{x}, -t) = e^{-i(\vec{p} \cdot \vec{x} / \hbar + \omega t)} = e^{i(-\vec{p} \cdot \vec{x} / \hbar - \omega t)}$$

(b).

$$\vec{\sigma} \cdot \hat{n} \chi_+(\hat{n}) = \chi_+(\hat{n}), \chi_+ = \begin{pmatrix} \cos(\beta/2)e^{-i\alpha/2} \\ \sin(\beta/2)e^{i\alpha/2} \end{pmatrix}$$

$$-i\sigma_2 \chi_+^*(\hat{n}) = -i\sigma_2 \begin{pmatrix} \cos(\beta/2)e^{i\alpha/2} \\ \sin(\beta/2)e^{-i\alpha/2} \end{pmatrix} = \begin{pmatrix} -\sin(\beta/2)e^{i\alpha/2} \\ \cos(\beta/2)e^{-i\alpha/2} \end{pmatrix}$$

Consider

$$\chi_+(\hat{n})|_{\beta \rightarrow \pi - \beta, \alpha \rightarrow \pi + \alpha} = \begin{pmatrix} -\sin(\beta/2)e^{i\alpha/2} \\ \cos(\beta/2)e^{-i\alpha/2} \end{pmatrix} = -i\sigma_2 \chi_+^*(\hat{n})$$

Therefore

$$\chi_-(\hat{n}) = \chi_+(\hat{n})|_{\beta \rightarrow \pi - \beta, \alpha \rightarrow \pi + \alpha} = -i\sigma_2 \chi_+^*(\hat{n})$$

5 Solution5

(a).

$$\Theta D(R)|j, m\rangle = \Theta e^{-i\vec{J} \cdot \hat{n} \theta / \hbar} |j, m\rangle = \Theta e^{-i\vec{J} \cdot \hat{n} \theta / \hbar} \Theta^{-1} \Theta |j, m\rangle$$

$$\Theta e^{-i\vec{J} \cdot \hat{n} \theta / \hbar} \Theta^{-1} = e^{+i(-\vec{J}) \cdot \hat{n} \theta / \hbar} = e^{-i\vec{J} \cdot \hat{n} \theta / \hbar}, \quad \Theta |j, m\rangle = (-1)^m |j, -m\rangle$$

Therefore

$$\Theta D(R)|j, m\rangle = \Theta e^{-i\vec{J} \cdot \hat{n} \theta / \hbar} |j, m\rangle = (-1)^m D(R)|j, -m\rangle$$

(b).

$$\Theta D(R)|j, m\rangle = \Theta \left[\sum_{m'} D(R)_{m', m} |j, m'\rangle \right]$$

$$L.H.S = (-1)^m D(R)|j, -m\rangle = (-1)^m \sum_{m'} D(R)_{-m', -m} |j, -m'\rangle$$

$$R.H.S = \sum_{m'} D_{m', m}^* \Theta |j, m'\rangle = \sum_{m'} D_{m', m}^*(R) (-1)^{m'} |j, -m'\rangle$$

So we have

$$D_{m', m}^*(R) = (-1)^{m-m'} D_{-m', -m}(R)$$

(c). For $j = 1/2$

$$\begin{aligned} \Theta |j, m\rangle &= \eta e^{-i\pi J_y / \hbar} K |j, m\rangle = \eta e^{-i\pi J_y / \hbar} |j, m\rangle = \eta \sum_{m'} D_{m', m}(\pi) |j, m'\rangle \\ &= \eta \sum_{m'} \delta_{m', -m} (-1)^{j+m} |j, m'\rangle = \eta (-1)^{j+m} |j, -m\rangle \end{aligned}$$

Choose $\eta = (-1)^{-j}$

$$\Theta |j, m\rangle = (-1)^m |j, -m\rangle = (i)^{2m} |j, -m\rangle$$

6 Solution6

$$H = \hbar^2 \begin{pmatrix} A & 0 & B \\ 0 & 0 & 0 \\ B & 0 & A \end{pmatrix}$$

Eigenvalues and eigenstates

$$\begin{aligned} E &= 0, & |1, 0 \rangle \\ E &= \hbar^2(A + B), & \frac{1}{\sqrt{2}}(|1, +1 \rangle + |1, -1 \rangle) \\ E &= \hbar^2(A - B), & \frac{1}{\sqrt{2}}(|1, +1 \rangle - |1, -1 \rangle) \end{aligned}$$

Assume A, B are real

$$\Theta H \Theta^{-1} = H$$

Because of

$$\Theta S_{x,y,z}^2 \Theta^{-1} = (-S_{x,y,z})^2 = S_{x,y,z}^2.$$

Therefore, H is invariant under time reversal.

$$\begin{aligned} \Theta |1, 0 \rangle &= |1, 0 \rangle \\ \Theta \frac{1}{\sqrt{2}}(|1, +1 \rangle + |1, -1 \rangle) &= \frac{1}{\sqrt{2}}(-|1, -1 \rangle - |1, +1 \rangle) = -\frac{1}{\sqrt{2}}(|1, +1 \rangle + |1, -1 \rangle) \\ \Theta \frac{1}{\sqrt{2}}(|1, +1 \rangle - |1, -1 \rangle) &= \frac{1}{\sqrt{2}}(-|1, -1 \rangle + |1, +1 \rangle) = \frac{1}{\sqrt{2}}(|1, +1 \rangle - |1, -1 \rangle) \end{aligned}$$

All states are invariant under time reversal.