

Direct 42 cont. Again expand about $\theta = 0 \Rightarrow$

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$$L = \frac{1}{2} M a^2 \dot{\theta}^2 - \frac{k a l_0 \sqrt{2}}{8} \theta^2 + M \Omega \lambda \cos \Omega t a \dot{\theta} + \text{terms of order 3}$$

Now work out the eqns of motion:

$$\frac{\partial L}{\partial \theta} = M a^2 \dot{\theta} + M a \Omega \lambda \cos \Omega t, \quad \frac{\partial L}{\partial \dot{\theta}} = -\frac{k a l_0 \sqrt{2}}{4} \theta$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = M a^2 \ddot{\theta} - M a \Omega^2 \lambda \sin \Omega t. \quad \therefore \text{eqns of motion are}$$

$$M a^2 \ddot{\theta} - M a \Omega^2 \lambda \sin \Omega t + \frac{k a l_0 \sqrt{2}}{4} \theta = 0 \quad \text{or}$$

$$\ddot{\theta} + \frac{k a l_0 \sqrt{2}}{4 M a^2} \theta = \Omega^2 \frac{\lambda}{a} \sin \Omega t, \quad \text{or}$$

$$\ddot{\theta} + \omega^2 \theta = \frac{\Omega^2 \lambda}{a} \sin \Omega t$$