

Direct 4a cont.

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$$= -(k/2)(2a^2 + l_0^2) + ka l_0 \sqrt{2} \left(\frac{\sin \theta}{2} - \sin \frac{\theta}{2} + \cos \frac{\theta}{2} \right)$$

Now expand in a power series in θ . The result is

$$-(k/2)(2a^2 + l_0^2) + ka l_0 \sqrt{2} - ka l_0 \sqrt{2} \left(\frac{\theta}{2} \right)^2 \frac{1}{2!} + O(\theta^3)$$

Note that the linear term in θ vanishes as required by the equilibrium condition. Consequently,

$$L = \frac{1}{2} Ma^2 \dot{\theta}^2 - \frac{ka l_0 \sqrt{2}}{8} \theta^2 + O(\theta^3) + \text{const}$$

$$\frac{\partial L}{\partial \theta} = -\frac{ka l_0 \sqrt{2}}{4} \theta, \quad \frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = Ma^2 \ddot{\theta} \Rightarrow \text{the eqns of motion}$$

$$Ma^2 \ddot{\theta} + \frac{ka l_0 \sqrt{2}}{4} \theta = 0 \Rightarrow \omega^2 = \frac{ka l_0 \sqrt{2}/4}{Ma^2}$$

or

$$\omega^2 = \frac{ka l_0 \sqrt{2}}{4Ma^2}$$