

Now A is small since $\vec{v}(0)$ is nearly $v_0 \hat{e}_z$.

Thus, to lowest order $t_e = \frac{l}{v_0}$. Putting this in for t_e we can find $x(t_e)$ and $y(t_e)$: 3/6
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$$x(t_e) = A \sin \delta - A \sin \left(\omega \frac{l}{v_0} + \delta \right)$$

$$y(t_e) = v_y^0 \frac{l}{v_0}$$

Expand out: using $\sin(\theta + \phi) = \sin \theta \cos \phi + \cos \theta \sin \phi$, etc.

$$x(t_e) = A \sin \delta - A \sin \left(\omega \frac{l}{v_0} \right) \cos \delta - A \cos \left(\omega \frac{l}{v_0} \right) \sin \delta$$

$$x(t_e) = \frac{v_0 - v_z^0}{\omega} \left[1 - \cos \frac{\omega l}{v_0} \right] + \frac{v_x^0}{\omega} \sin \frac{\omega l}{v_0}$$

$$y(t_e) = v_y^0 \frac{l}{v_0}$$

Let us write $v_z^0 = v_0 \cos \theta$,

$$v_x^0 = v_0 \sin \theta \cos \phi \quad v_y^0 = v_0 \sin \theta \sin \phi$$

with θ small.

Then $v_z^0 - v_0 = -v_0 (1 - \cos \theta) \sim \theta^2$, and

to order θ we have

$$x(t_e) = \frac{v_x^0}{\omega} \sin \omega \frac{l}{v_0}$$

$$y(t_e) = v_y^0 \frac{l}{v_0}$$