

$$\Theta_1 = A (2L^2)^{-1} \sqrt{\frac{m_1 + m_2}{m_2}} \left[(m_1 + m_2)^{\frac{1}{2}} - (m_1 + m_2) m_2 \right]^{-\frac{1}{2}} \left[\cos \omega_+ t + \cos \omega_- t \right]$$

or

$$\Theta_1 = A (2L^2)^{-1} \sqrt{\frac{4m_1 m_2}{m_1 + m_2}} \left[m_1 (m_1 + m_2) \right]^{-\frac{1}{2}} \left[\right] \Rightarrow$$

$$\Theta_1 = A (2L^2)^{-1} \sqrt{\frac{m_1}{m_2}} \left[\cos \omega_+ t + \cos \omega_- t \right]$$

Next work on Θ_2 :

$$\Theta_2 = A \left[- (e_1^z, n^T) (e_2^z, n^-) \right] \left\{ \cos \omega_+ t - \cos \omega_- t \right\}$$

$$= A \left[\frac{m_1 + m_2}{m_2} \left\{ (2L^2) \left[(m_1 + m_2) + \sqrt{m_2 (m_1 + m_2)} \right] \right\}^{-\frac{1}{2}} \left\{ (2L^2) \left[(m_1 + m_2) - \sqrt{m_2 (m_1 + m_2)} \right] \right\}^{-\frac{1}{2}} \right]$$

$$\sim A (2L^2)^{-1} \frac{m_1 + m_2}{m_2} \left[m_1 (m_1 + m_2) \right]^{-\frac{1}{2}} \left[\cos \omega_+ t - \cos \omega_- t \right]$$

$$= A (2L^2)^{-1} \sqrt{\frac{m_1}{m_2}} \sqrt{\frac{m_1 + m_2}{m_2}} \left[\cos \omega_+ t - \cos \omega_- t \right]. \text{ Finally, Fixing } A \Rightarrow$$