

If $\omega_2^* \neq 0$ and ω_1^*, ω_3^* are $\approx \epsilon$, write

$$\vec{\omega} = \epsilon_1 \hat{e}_1 + \omega_2^* \hat{e}_2 + \epsilon_3 \hat{e}_3$$

The torque

free Euler eqns then become

$$\dot{\epsilon}_1 I_1^* + \omega_2^* \epsilon_3 (I_3^* - I_2^*) = 0$$

$$\dot{\omega}_2^* I_2^* + \epsilon_3 \epsilon_1 (I_1^* - I_3^*) = 0 \quad \leftarrow \text{This eqn says } \omega_2^* = \text{const} + O(\epsilon^2)$$

$$\dot{\epsilon}_3 I_3^* + \epsilon_1 \omega_2^* (I_2^* - I_1^*) = 0$$

These equations with $\omega_2^* \approx \text{const}$ become

$$w) \quad \dot{\epsilon}_1 + \epsilon_3 \left[\frac{\omega_2^* (I_3^* - I_2^*)}{I_1^*} \right] = 0$$

$$u) \quad \dot{\epsilon}_3 + \epsilon_1 \left[\frac{\omega_2^* (I_2^* - I_1^*)}{I_3^*} \right] = 0$$

Differentiating u) + substituting into w) \Rightarrow

$$\begin{aligned} \ddot{\epsilon}_1 + \Omega_2^2 \epsilon_1 &= 0 \\ \ddot{\epsilon}_3 + \Omega_2^2 \epsilon_3 &= 0 \end{aligned}$$

where

$$\Omega_2^2 = \omega_2^{*2} \frac{(I_2^* - I_3^*)(I_2^* - I_1^*)}{I_1^* I_3^*}$$

Note $I_2^* - I_3^* < 0 + I_2^* - I_1^* > 0 \Rightarrow \Omega_2^2 < 0$.

Thus, $\epsilon_1 + \epsilon_3$ grow exponentially, + motion is unstable. In the other cases of motion initially about e_1^* or e_3^* we find Ω_1^2 Thus, ^{this} motion is stable.

$$\Omega_1^2 = \omega_1^{*2} \frac{(I_1^* - I_2^*)(I_1^* - I_3^*)}{I_3^* I_2^*} > 0 + \Omega_3^2 = \frac{\omega_3^{*2} (I_3^* - I_1^*)(I_3^* - I_2^*)}{I_2^* I_1^*} > 0$$