

$$p_\phi = \frac{\partial L}{\partial \dot{\phi}} = m\ell^2 \dot{\phi}, \quad \frac{\partial L}{\partial \phi} = -mg\ell \sin \phi, \quad \frac{\partial}{\partial t} \frac{\partial L}{\partial \dot{\phi}} = m\ell^2 \ddot{\phi} + 2m\ell \dot{\ell} \dot{\phi}$$

$$\Rightarrow m\ell^2 \ddot{\phi} + 2m\ell \dot{\ell} \dot{\phi} + mg\ell \sin \phi = 0. \quad \mathcal{H} = p_\phi \dot{\phi} - L \Rightarrow$$

$$\mathcal{H} = m\ell^2 \dot{\phi}^2 - \frac{1}{2}m(\dot{\ell}^2 + \ell^2 \dot{\phi}^2) - mg\ell \cos \phi \Rightarrow \mathcal{H} = \frac{1}{2}m\ell^2 \dot{\phi}^2 - mg\ell \cos \phi - \frac{1}{2}m\dot{\ell}^2.$$

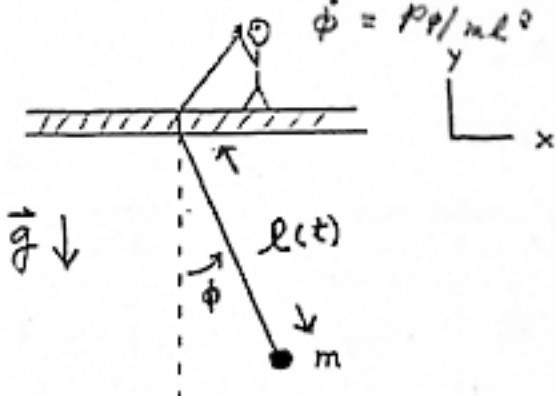
10. (15 pts) Consider a simple plane pendulum whose length $\ell(t)$ is controlled by Ehrenfest's ghost.

$$x = \ell \sin \phi, \quad y = -\ell \cos \phi$$

$$\dot{x} = \dot{\ell} \sin \phi + \ell \cos \phi \dot{\phi}$$

$$\dot{y} = -\dot{\ell} \cos \phi + \ell \sin \phi \dot{\phi}$$

$$T = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2) = \frac{1}{2}m(\dot{\ell}^2 + \ell^2 \dot{\phi}^2)$$



Assume that $\ell(t)$ is a known function. $\nabla = m\vec{g}\vec{y} = -mg\ell \cos \phi$

- (a) Using ϕ as a generalized coordinate, write the Lagrangian for the pendulum.

$$L(\phi, \dot{\phi}, t) = \frac{1}{2}m(\dot{\ell}^2 + \ell^2 \dot{\phi}^2) + mg\ell \cos \phi$$

- (b) Find the differential equation of motion for $\phi(t)$.

$$m\ell^2 \ddot{\phi} + 2m\ell \dot{\ell} \dot{\phi} + mg\ell \sin \phi = 0$$

or

$$\ddot{\phi} + 2(\dot{\ell}/\ell) \dot{\phi} + \frac{g}{\ell} \sin \phi = 0$$

- (c) Find the Hamiltonian.

$$H(\phi, p_\phi, t) = \frac{p_\phi^2}{2m\ell^2} - mg\ell \cos \phi - \frac{1}{2}m\dot{\ell}^2$$