(4 pts) Consider a particle of mass m constrained to move without friction on the curve x = 0, z = y<sup>2</sup> under the influence of gravity.

$$J = T - V$$
,  $T = \frac{m}{2} (\dot{x}^2 + \dot{y}^2 + \dot{z}^2)$   
 $\dot{z} = x = c$ ,  $\dot{z} = 2y\dot{y}$ ,  $V = mqz$   
 $\dot{z} = mqy^2$ 

Its Lagrangian is given by

$$\mathcal{L}(y,\dot{y},t) = \frac{m}{4} \left( 1 + 4 y^2 \right) (\dot{y})^2 - mgy^2$$

 (3 pts) Consider a particle of mass m and charge q moving in an electromagnetic field described by the scalar and vector potential φ(r, t) and A(r, t). Its Lagrangian in MKS units is given by

$$\mathcal{L}(r,v,t) = \frac{1}{2} m \vec{x} \cdot \vec{v} + q \vec{v} \cdot \vec{A} (\vec{r},t) - q \phi(\vec{r},t)$$

6. (6 pts) A system with 3 degrees of freedom has the peculiar Lagrangian

$$\begin{array}{rcl} \mathcal{L}(q,\dot{q},t) & = & \dot{q}_{1}^{2}q_{2}\cos q_{3} + \dot{q}_{2}^{2}q_{2}q_{3} + \dot{q}_{3}^{2}\tan(q_{2}q_{3}) \\ & + & \dot{q}_{1}\dot{q}_{2}\dot{q}_{3} + q_{2}\exp q_{3} + ct^{5}q_{2}q_{3}. \end{array} \qquad \begin{array}{rcl} \frac{\partial}{\partial q_{1}} & = & 0 \\ & & & & \\ & & & & \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{1}} & = & c = \\ & & & \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ & & & \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{1}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{1}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{\partial q_{2}} & = & c = \\ \end{array} \begin{array}{rcl} \frac{\partial}{$$

It has the constant of motion

$$P_{i} = \frac{\partial \mathcal{L}}{\partial \hat{q}_{i}} = 2\hat{q}_{i} q_{2} \cos q_{3} + \hat{q}_{2} \hat{q}_{3} = cn \partial \hat{q}_{3}$$

$$\frac{\partial \mathcal{L}}{\partial t} = 0 \Rightarrow \mathcal{H} = cn \partial \hat{q}_{i} = 0, \text{ it has the additional constant of motion } \mathcal{H} = \sum_{i=1}^{n} \frac{\partial \mathcal{L}}{\partial \hat{q}_{i}} \hat{q}_{i} - \mathcal{L} \Rightarrow \hat{q}_{3} = (\hat{q}_{1})^{2} q_{1} \cos q_{3} + (\hat{q}_{2})^{2} q_{2} q_{3} + (\hat{q}_{3})^{2} + an (q_{2}) q_{3}$$

$$+ 2\hat{q}_{1} \hat{q}_{2} \hat{q}_{3} - q_{2} \exp q_{3} = cn \partial \hat{q}_{3}$$

$$+ 2\hat{q}_{1} \hat{q}_{2} \hat{q}_{3} - q_{2} \exp q_{3} = cn \partial \hat{q}_{3}$$