

HW2.

1. $x = A \cos(\omega t + \phi)$

(a) $t = 0$, $x(t=0) = A \cos \phi$ (cm)

(b) $v = \frac{dx}{dt} = -A\omega \sin(\omega t + \phi)$ (cm/s)

(c) $a = \frac{dv}{dt} = -A\omega^2 \cos(\omega t + \phi)$ (cm/s²)

(d) Period $T = \frac{2\pi}{\omega}$ s

Amplitude A

2.

A simple harmonic oscillator takes 12.5s to undergo six complete vibrations.

(a) Period $T = \frac{12.5}{6} = 2.08$ (s)

(b) Frequency $f = \frac{1}{T}$ (Hz)

(c) Angular frequency $\omega = \frac{2\pi}{T}$ (rad/s)

3. A block of unknown mass m ,

Spring constant $k = 6.00$ N/m

Amplitude $A = 10.5$ cm

When the block is halfway between its equilibrium position and the end point, speed $v = 27.0$ cm/s

$$x=0$$

$$\textcircled{A} \quad x_A = \frac{1}{2}A$$

$$\textcircled{B} \quad x_B = A$$

$$V_A = 27 \text{ cm/s} \quad V_B = 0$$

Energy is conserved.

$$E_{\textcircled{A}} = \frac{1}{2} m V_A^2 + \frac{1}{2} K x_A^2 = \frac{1}{2} m V_B^2 + \frac{1}{2} K x_B^2 = E_{\textcircled{B}}$$

$$\Rightarrow m = \frac{2}{V_A^2} \left[\frac{1}{2} K A^2 - \frac{1}{2} K \left(\frac{A}{2} \right)^2 \right]$$

$$= \frac{2}{(27 \times 10^{-2})^2} \left[\frac{1}{2} \times 6 \times (10.5 \times 10^{-2})^2 - \frac{1}{2} \times 6 \times \left(\frac{1}{2} \times 10.5 \times 10^{-2} \right)^2 \right]$$

4.

$$m = 65 \text{ g}, \quad K = 35 \text{ N/m}, \quad \text{Amplitude } A = 8 \text{ cm}$$



When the spring is stretched maximum, $V=0$.

$$E_{\text{tot}} = \frac{1}{2} m V^2 + \frac{1}{2} K x^2 = \frac{1}{2} K A^2$$

$$(b) \quad E_{\text{tot}} = \frac{1}{2} K A^2 = \frac{1}{2} m V^2 + \frac{1}{2} K x^2 \quad (x = 1.05 \text{ cm})$$

$$\Rightarrow V = \sqrt{\frac{1}{m} K (A^2 - x^2)}$$

$$(c) \quad E_{\text{kinetic}} = E_{\text{tot}} - E_{\text{pot}} = \frac{1}{2} K A^2 - \frac{1}{2} K x^2 \quad (x = 3 \text{ cm})$$

$$(d) \quad E_{\text{pot}} = \frac{1}{2} K x^2$$

5. Amplitude $A = 3.70 \text{ cm}$

Spring Constant $k = 250 \text{ N/m}$

Mass of the block $m = 0.8 \text{ kg}$

(a) Mechanical energy E

$$E_{\text{tot}} = E_{\text{kinetic}} + E_{\text{potential}}$$

$$= \frac{1}{2} m v^2 + \frac{1}{2} k x^2$$

$$= \frac{1}{2} k A^2$$

(b) The maximum speed v_{max}

when the potential energy is zero, ($x = 0$),

$$v = v_{\text{max}}$$

$$E_{\text{tot}} = \frac{1}{2} k A^2 = \frac{1}{2} m v_{\text{max}}^2$$

$$\therefore v_{\text{max}} = \sqrt{\frac{k}{m}} A$$

(c) The maximum acceleration a_{max}

When the spring stretched maximum,

force is maximum and acceleration is also maximum.

$$F = kx = ma$$

$$\therefore a_{\text{max}} = \frac{k}{m} x_{\text{max}} = \frac{k}{m} A$$

6. Amplitude $A = 6\text{ cm}$.

What is the position x for spring's speed to equal $3/4$ of its maximum speed v_{max} ?

$$E_{\text{tot}} = \frac{1}{2} k A^2 = \frac{1}{2} m v^2 + \frac{1}{2} k x^2$$
$$= \frac{1}{2} m v_{\text{max}}^2$$

$$\textcircled{1}: \frac{1}{2} k A^2 = \frac{1}{2} m v_{\text{max}}^2 \Rightarrow v_{\text{max}} = \sqrt{\frac{k}{m}} A$$

$$\textcircled{2}: \frac{1}{2} k A^2 = \frac{1}{2} m \left(\frac{3}{4} \cdot \sqrt{\frac{k}{m}} A \right)^2 + \frac{1}{2} k x^2$$

$$\therefore x = \pm \left[A^2 - \frac{9}{16} A^2 \right]^{1/2} = \pm \sqrt{\frac{7}{16}} A$$

7. $\theta = (0.320 \text{ rad}) \cos \omega t$. $\omega = 7.93 \text{ rad/s}$

(a) period $T = \frac{2\pi}{\omega}$

(b) length of the pendulum, l

$$T = 2\pi \sqrt{\frac{l}{g}} = \frac{2\pi}{\omega} , g = 9.8 \text{ m/s}^2$$

$$\therefore l = \frac{g}{\omega^2}$$

8. The period of the pendulum T

$$T = 2\pi \sqrt{\frac{l}{g_{\text{eff}}}}$$

(a) An elevator is accelerating upward at 4 m/s^2

$$g_{\text{eff}} = 9.8 + 4$$

(b) accelerating downward at 4 m/s^2

$$g_{\text{eff}} = 9.8 - 4$$

$$(c) \quad g_{\text{eff}} = \sqrt{9.8^2 + 4^2}$$

horizontally accelerating
at 4 m/s^2