

Physics for Scientists and Engineers



Chapter 5 Force and Motion

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Force

- Forces are what cause any change in the velocity of an object

$$\vec{a}_{\text{avg}} = \frac{\Delta \vec{v}}{\Delta t}$$

- The *net force* is the vector sum of all the forces acting on an object
 - Also called total force, resultant force, or unbalanced force



Forces

- A force acts on an object
 - Forces do not exist unless acting on something
- Something (agent) has to exert a force
- Forces are **vectors**
- Contact forces: involve physical contacts
 - e.g. billiard ball collisions
- Long-range forces: act through empty space
 - e.g. gravity, electric & magnetic fields



Fundamental Field Forces

- Gravitational force
 - Between two objects (with mass)
- Electromagnetic forces
 - Between two charges
- Nuclear force
 - Between subatomic particles
- Weak forces
 - Arise in certain radioactive decay processes



Zero Net Force

- When the **net force** is equal to zero, the acceleration is zero (Newton's 1st Law)
 - The **velocity is constant**, **not necessarily 0**
- *Equilibrium* occurs when the net force is equal to zero
 - The object, if at rest, will remain at rest
 - If the object is moving, it will continue to move at a constant velocity



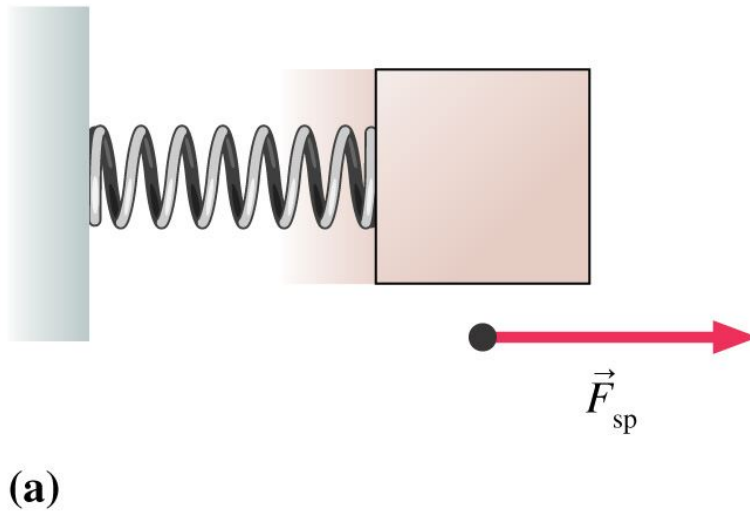
Forces – Weight: \mathbf{F}_G

- The **gravitational pull** on an object is called weight
 - Near the earth's surface, weight = $|\mathbf{F}_G| = mg$
- The weight vector always points down
 - More precisely, toward the center of the earth
- Mass and weight are two **different** quantities
 - Mass is an inherent quantity of an object
 - Weight varies with location, i.e. weight is less at higher altitude

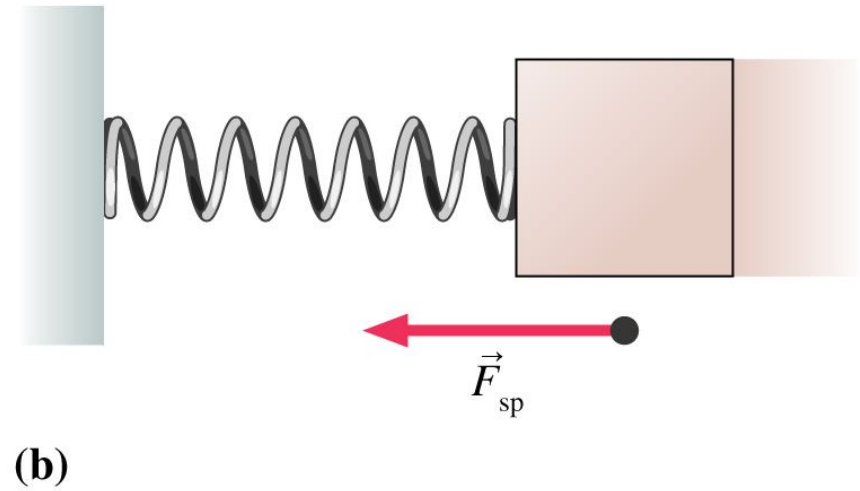
Forces – Spring Forces

■ Push and pull by a spring

A compressed spring exerts a pushing force on an object.

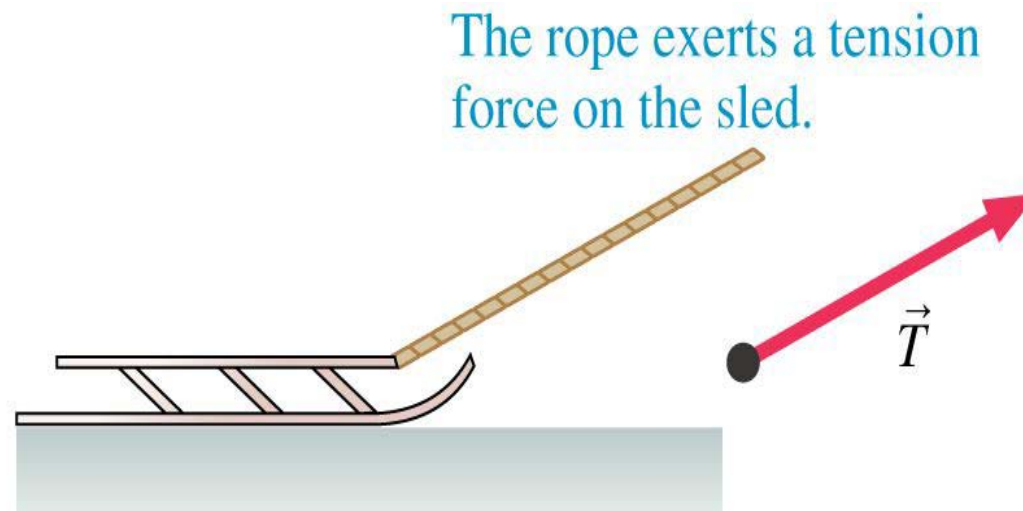


A stretched spring exerts a pulling force on an object.



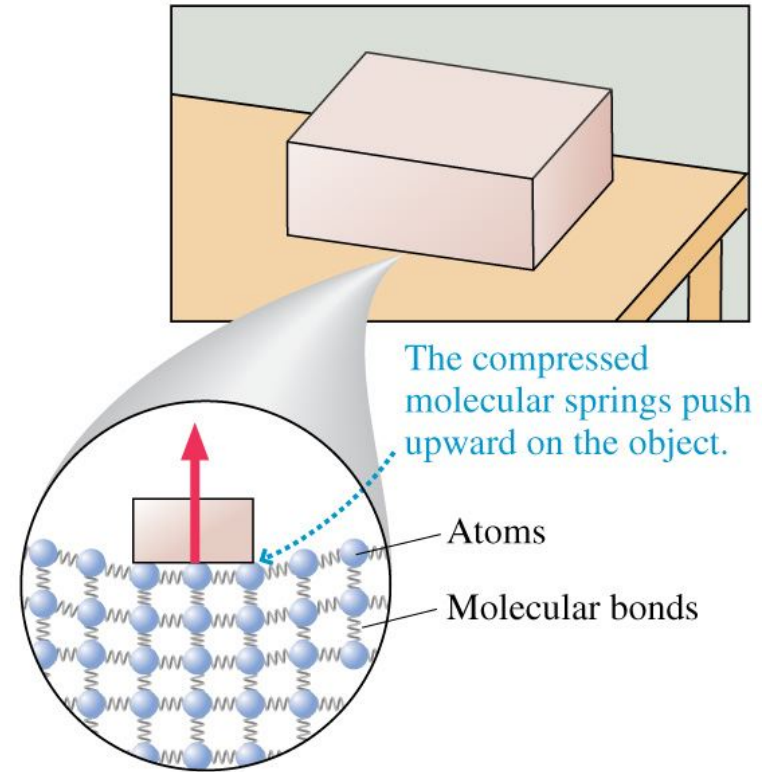
Forces – Tension: T

- Pulling forces in strings are called tension
 - Tension forces do not push on an object
- The tension is always **along** the string



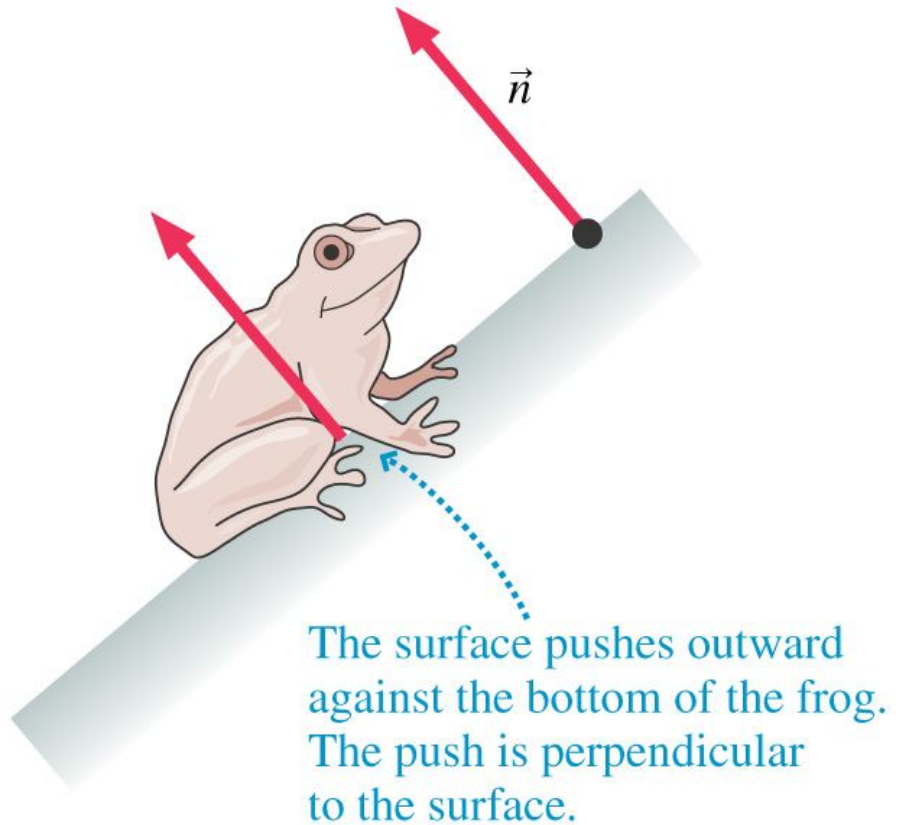
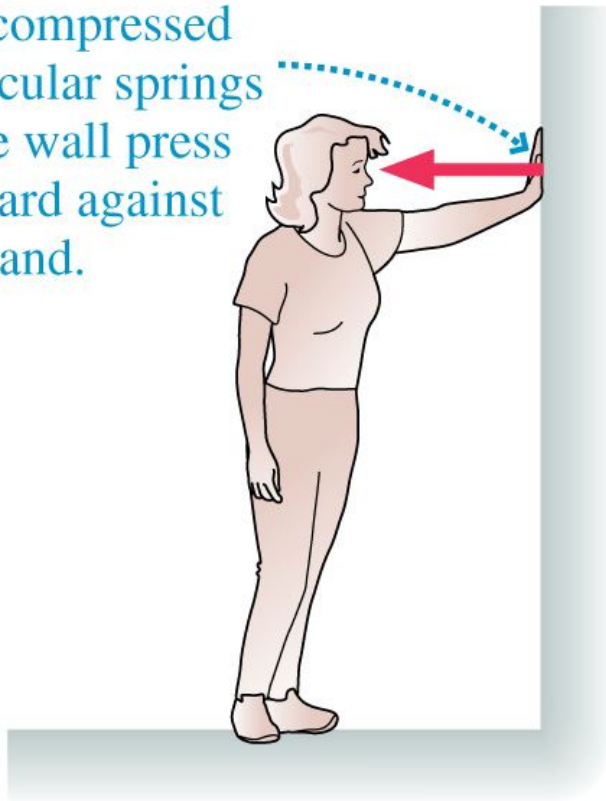
Forces – Normal Forces: n

- Normal forces are exerted by a surface due to compressed atomic "springs" in the surface
 - They are reactions to forces exerted on the surface
- Normal forces are always **perpendicular** to the surface



Forces – Normal Forces, cont

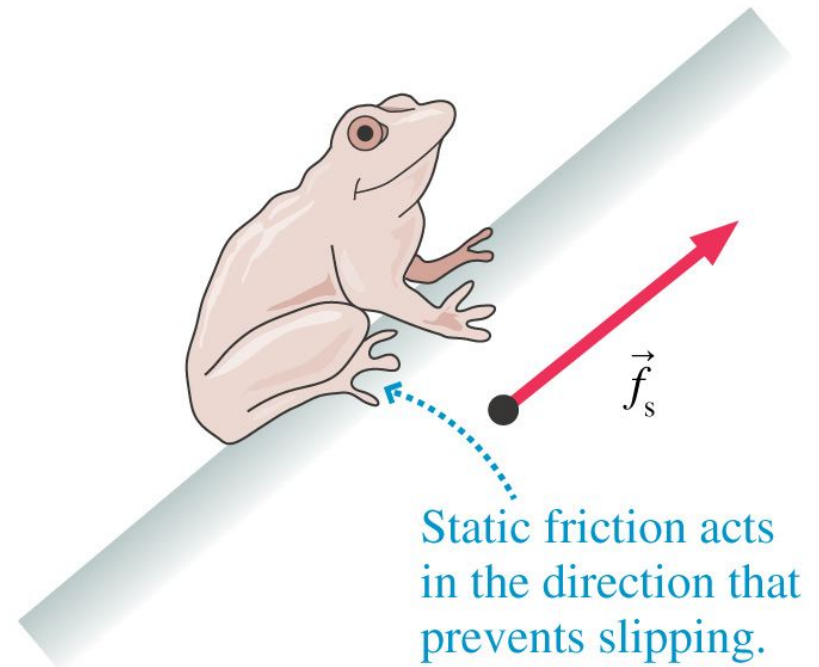
The compressed molecular springs in the wall press outward against her hand.



The surface pushes outward against the bottom of the frog. The push is perpendicular to the surface.

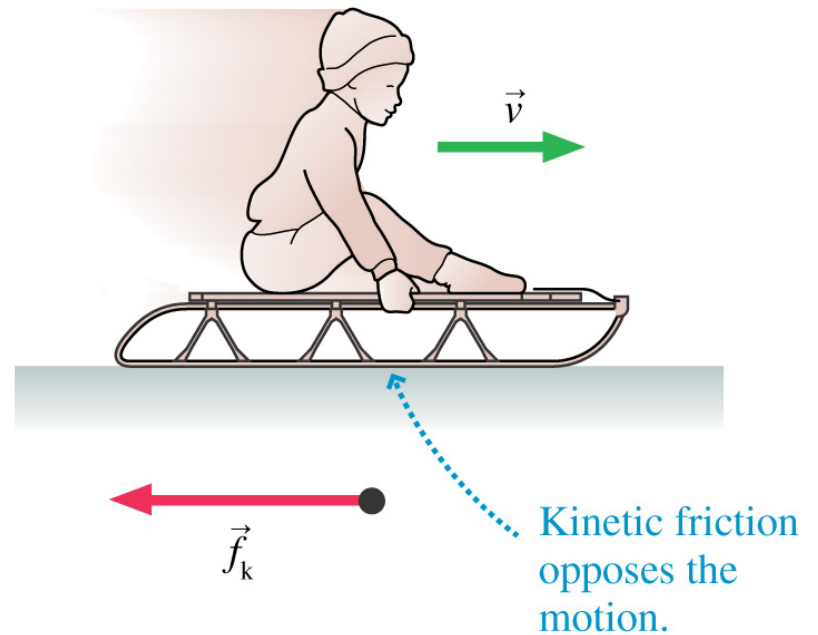
Forces – Static Friction: f_s

- **Static** friction is a force that keeps an object from moving along a surface
- The static friction force points **opposite to the direction an object would move** if there were no friction



Forces – Kinetic Friction: f_k

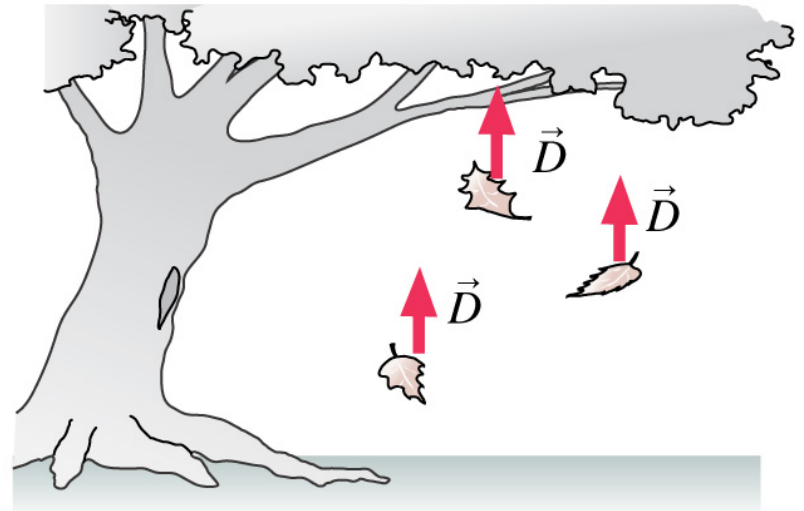
- **Kinetic** friction force opposes the motion of an object moving on a surface
- The kinetic friction force points in the direction **opposite to the velocity vector**



Forces – Drag Forces

- Drag forces are a kind of friction force of an object moving through a fluid media (gas or liquid)
- The drag force is opposite to the velocity vector

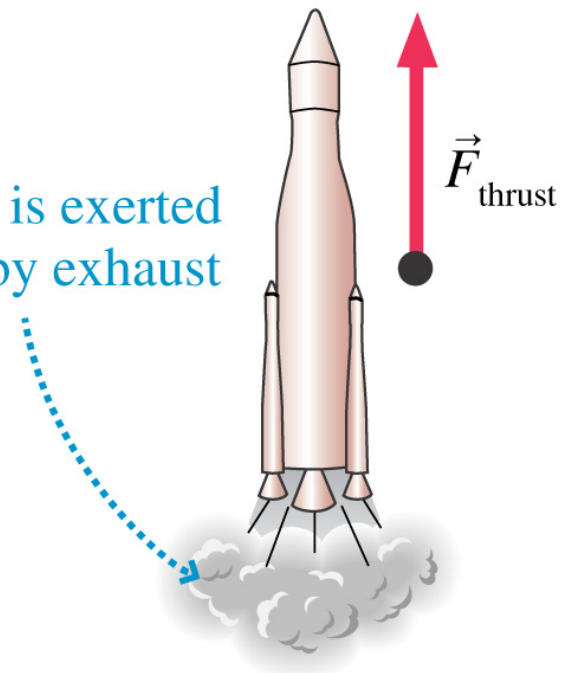
Air resistance is a significant force on falling leaves. It points opposite the direction of motion.



Forces – Thrust

- Thrust is the force that propels jet planes and rockets

Thrust force is exerted on a rocket by exhaust gases.





Electric & Magnetic Forces

- Electric and magnetic forces act over long distances like gravitational forces.
- These force act on charged particles like electrons or protons



Newton's First Law

- An object at rest will **stay at rest**, or an object that is moving will continue to **move at constant velocity**, if and only if the **net** (i.e. **total**) **force** acting on it is zero

$$\sum \vec{F} = 0 \iff \vec{v} = \text{constant}$$

- Objects with no net force acting on them are said to be in equilibrium



Newton's Second Law

- The **acceleration** of an object is directly proportional to the **net force** acting on it and inversely proportional to its mass

$$\vec{a} = \frac{\sum \vec{F}}{m}$$

- Algebraically we can also write

$$\sum \vec{F} = m\vec{a}$$



Newton's Second Law, cont

- $\Sigma \mathbf{F}$ is the **net** force
 - This is the **vector sum** of all the forces acting on the object
- Newton's Second Law can be expressed in terms of components:

$$\sum F_x = ma_x$$

$$\sum F_y = ma_y$$

$$\sum F_z = ma_z$$



Units of Force

Table 5.1

Units of Mass, Acceleration, and Force ^a			
System of Units	Mass	Acceleration	Force
SI	kg	m/s ²	N = kg · m/s ²
U.S. customary	slug	ft/s ²	lb = slug · ft/s ²

^a 1 N = 0.225 lb.



Inertia and Mass

- The tendency of an object to resist any attempt to change its velocity is called *inertia*
- *Mass* is that property of an object that specifies how much resistance an object exhibits to changes in its velocity
 - Sometimes this is called *inertial mass* to distinguish it from *gravitational mass*
 - Mass is a *scalar*

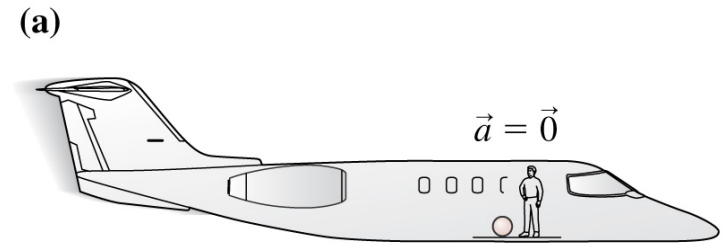


Inertial Frames

- Any reference frame (i.e. coordinate system) in which Newton's Laws are valid is an **inertial frame**
 - If $\mathbf{a} = 0$ in some reference system only when $\mathbf{F}_{\text{net}} = 0$, that reference frame is an inertial frame
- Generally, **non-accelerating** reference frames are inertial frames

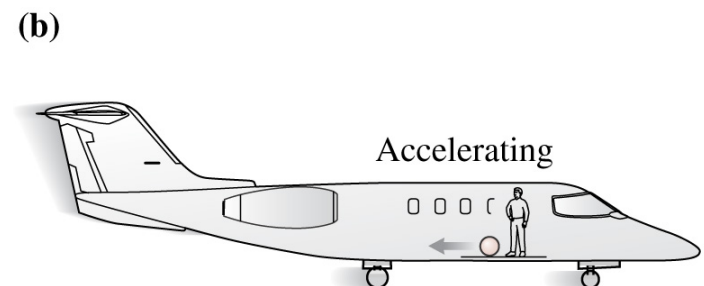
Inertial & Non-Inertial Frames

- In the **non-accelerating** plane, the ball stays in place wrt the plane with no horizontal force acting on it
⇒ This is an **inertial** frame
- In the **accelerating** plane, the ball accelerates backward with no horizontal force acting on it
⇒ This is a **non-inertial** frame



The ball stays in place.

A ball with no horizontal forces stays at rest in an airplane cruising at constant velocity. The airplane is an inertial reference frame.



The ball rolls to the back.

The ball rolls to the back of the plane during takeoff. An accelerating plane is not an inertial reference frame.

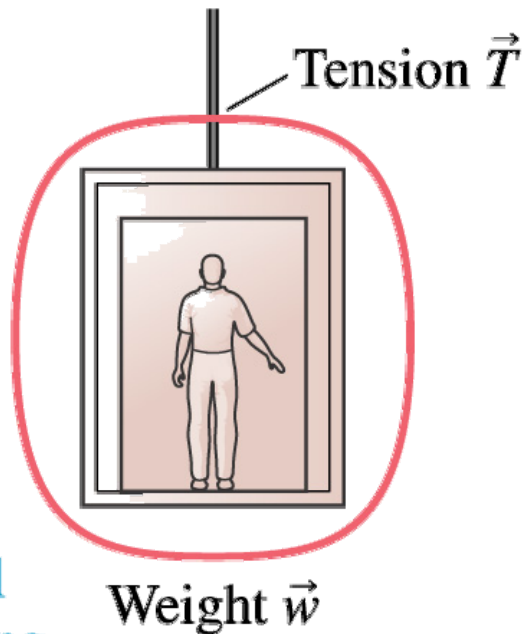


Free Body Diagrams

- A free body diagram shows all the forces acting on a body
 - Identify **all** the forces **acting on the object**
 - Draw a coordinate system
 - Represent the object as a dot at the origin
 - Draw vectors representing each of the identified forces
 - Draw and label the ***net force*** vector
- Free body diagrams facilitate calculations by showing the forces present

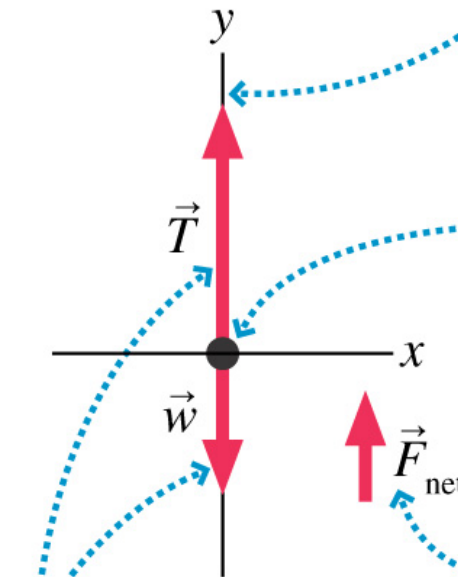
Elevator Accelerates Upward

Force identification



- 1 Identify all forces acting on the object.

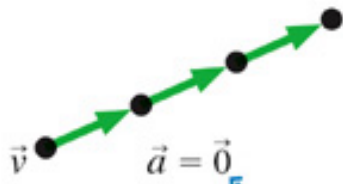
Free-body diagram



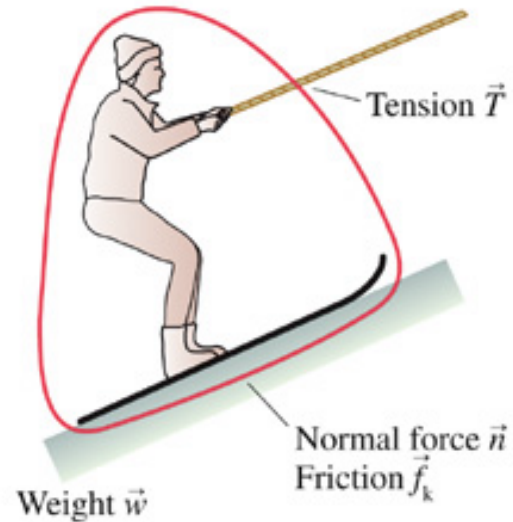
- 2 Draw a coordinate system.
- 3 Represent the object as a dot at the origin.
- 4 Draw vectors for the identified forces.
- 5 Draw and label \vec{F}_{net} beside the diagram.

Skier Pulled up a Hill

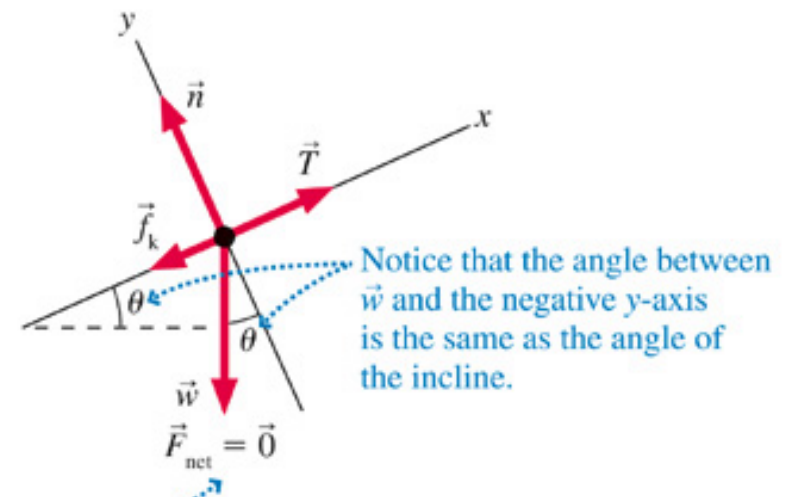
Motion diagram



Force identification



Free-body diagram



Check that \vec{F}_{net} matches \vec{a} .